Global Optimization

for practical engineering applications

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CEE 696

1. Global Optimization

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Global optimization

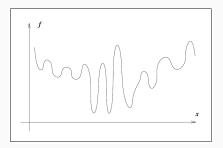


Figure 1: Fig 2.2 from Nocedal & Wright [2006]

- We have learned "local" optimization methods
- How can we solve the optimization problem like one with objective function in Figure 1?

When global optimization is needed?

- \cdot We saw Newton's method converges fast to the (local) optimum
- What if our objective function is very complex with many local optima as in Figure 1?
- \cdot One solution might be the one we start multiple initial guesses
- In many nonlinear optimization problems, the objective function *f* has a large number of local minima and maxima.
- Furthermore, *f* may be non-differentiable and non-continuous.
- Global optimization finds the maximum or minimum over all input values, as opposed to finding local minima or maxima.

- 1. Formulate/modify a global optimization problem into a tractable one with local optimization (e.g., convex optimization)
- 2. Use global optimization methods

Here, we focus on global optimization methods for general optimization problems.

If time is allowed, we will cover convex optimization.

Equation (Local) Minimizers

leastsq(func, x0[, args, Dfun, full_output,])	Minimize the sum of squares of a set of equations.
least_squares(fun, x0[, jac, bounds,])	Solve a nonlinear least-squares problem with bounds on the variables.
nnls(A, b)	Solve argmin_x Ax - b _2 for x>=0 .
lsq_linear(A, b[, bounds, method, tol,])	Solve a linear least-squares problem with bounds on the variables.

Global Optimization¶

basinhopping(func, x0[, niter, T, stepsize,])	Find the global minimum of a function using the basin-hopping algorithm
brute(func, ranges[, args, Ns, full_output,])	Minimize a function over a given range by brute force.
<pre>differential_evolution(func, bounds[, args,])</pre>	Finds the global minimum of a multivariate function.

Rosenbrock function

rosen(x)	The Rosenbrock function.
rosen_der(x)	The derivative (i.e.
rosen_hess(x)	The Hessian matrix of the Rosenbrock function.

- deterministic approach vs. stochastic approach
- stochastic, metaheuristic approaches are popular in engineering because they are easy to use
 - Simulated Annealing
 - Evolutionary Computation
 - Genetic Algorithm (GA)
 - Differential Evolution
 - \cdot particle swarm optimization, ant colony optimization and so on

Global optimization algorithms - stochastic approach

- Smart random search
- Computational cost (number of objective function evaluation) is high
- They are random, i.e., optimization result can change in every run
- Easy to implement your numerical simulation considered as black box
- No guarantee for convergence.

Simulated Annealing (Basin Hopping in scipy.optimize)

- A probabilistic technique for approximating the global optimum of a given function
- Name comes from metal annealing, heating and cooling of a material to increase the size of its crystals and reduce their defects
- Adapted from Metropolis-Hastings algorithms in 1953, which is used to generate sample states of thermodynamic system
- "basinhopping" in scipy.optimization ("simulated annealing" has been deprecated)

Simulated Annealing (Basin Hopping in scipy.optimize)

- \cdot A metal is heated to a high temperature
- \cdot The metal is gradually cooled on a specific schedule you specify
- As the metal cools, its atoms settle into an optimal (thermal-equilibrium) crystalline structure
- Annealing improves the cold-working properties of metal

- 1. Start with initial guess
- 2. Calculate energy E of initial guess (i.e., objective value)
- 3. Set initial temperature T
- 4. While T > cutoff/stopping T
 - 4.1 find a test solution
 - 4.2 Calculate E of the solution (i.e., objective value)
 - 4.3 δ = obj(test) obj(previous solution)
 - 4.4 if δ < 0: update solution and obj
 - 4.5 elif exp $\left(-\frac{\delta}{\tau}\right)$ > random.uniform(0, 1): update solution and obj
 - 4.6 decrease T

5. End

- Early in the search, SA explores the decision variable space
- As the search progresses, SA refines the search

• https://www.youtube.com/watch?v=iaq_Fpr4KZc

func Function to be optimized

x0 initial guess

T temperature parameter for the accept or reject criterion

minimizer_kwargs arguments for local optimization routine
 take_step user-defined step-taking algorithm
 accept_test user-defined step-acceptance algorithm
 callback function called for all minimum found
 interval interval for how often to update the stepsize

Download and run the example script http://www2.hawaii.edu/~jonghyun/classes/S18/ CEE696/files/example_basinhopping.py

- Developed by John Holland in 1975, many developments since then
- applications to real world problems
- Mimics mechanics of natural selection and genetics

- 1. Create Initial population
- 2. Selection individuals
- 3. Crossover & Mutation
- 4. Evaluation Fitness function
- 5. Repeat 2 5 until converges

- Let's assume our decision variable x is an integer \in [0, 127] for an optimization problem.
- with x' = bin(x), i.e., string represented in 6-length binary
- For example, x' can be 000000 (0), 000001 (1), 000010 (2), 000011 (3), ..., 111111 (127).
- Then generate "n" number of random strings (chromosome). This is our initial population.
- For example, we have an initial population of 6 parents:
- 001000, 010010, 101110, 000101, 100000, 010111
- Their fitness (of survival) is determined by user-defined objective function, i.e., obs(x)

Now we are generating offsprings of initial population. We are mating parent: 101110, 000101

Crossover: choose one or two points in the chromosome

- 1. One point crossover: 101110, 000101 => 101101, 000110
- 2. Two point crossover: 101110, 000101=> 100110, 001101

Mutation:

1. Bit inversion 1 => 0, 0 => 1

Create n offspring for the new generation and repeat this step until the maximum number of iterations.

GA is similar to differential evolution algorithm and python offers differential_evolution

differential_evolution(func, bounds, args=(),
 strategy='best1bin', maxiter=1000,
 popsize=15, tol=0.01, mutation=(0.5, 1),
 recombination=0.7, seed=None,
 callback=None, disp=False, polish=True,
 init='latinhypercube', atol=0)

strategy The differential evolution strategy to use
popsize A multiplier for setting the total population size. The
population has popsize * len(x) individuals.
mutation user-defined step-taking algorithm

recombination crossover probability

seed random seed for pseudo random algorithm

init population initialization method (latinhypercube or random)

from scipy.optimize import rosen, differential_evolution
bounds = [(0,2), (0, 2), (0, 2), (0, 2), (0, 2)]
result = differential_evolution(rosen, bounds)
print(result.x)
%(array([1., 1., 1., 1., 1.])
print(result.fun)
%1.9216496320061384e-19

More like deterministic optimization technique

ranges grid points or bounds for function evaluationsNs a number of grid points if bounds are defined in rangesfinish a local optimization can be called with the result of brute force minimization as initial guess

Use global optimization approaches for our previous examples basinhopping:

https://www2.hawaii.edu/~jonghyun/classes/S18/ CEE696/files/opt_max_pumping_basinhopping.py

differential differential_evolution:

https://www2.hawaii.edu/~jonghyun/classes/S18/ CEE696/files/opt_max_pumping_DE.py