An underwater photograph showing a diver and a submersible. The diver is on the left, and the submersible is on the right. The water is clear and blue. The submersible has a red buoy and a black camera. A circular warning label is visible on the submersible, which reads "DO NOT PLANT BUCK VALVE".

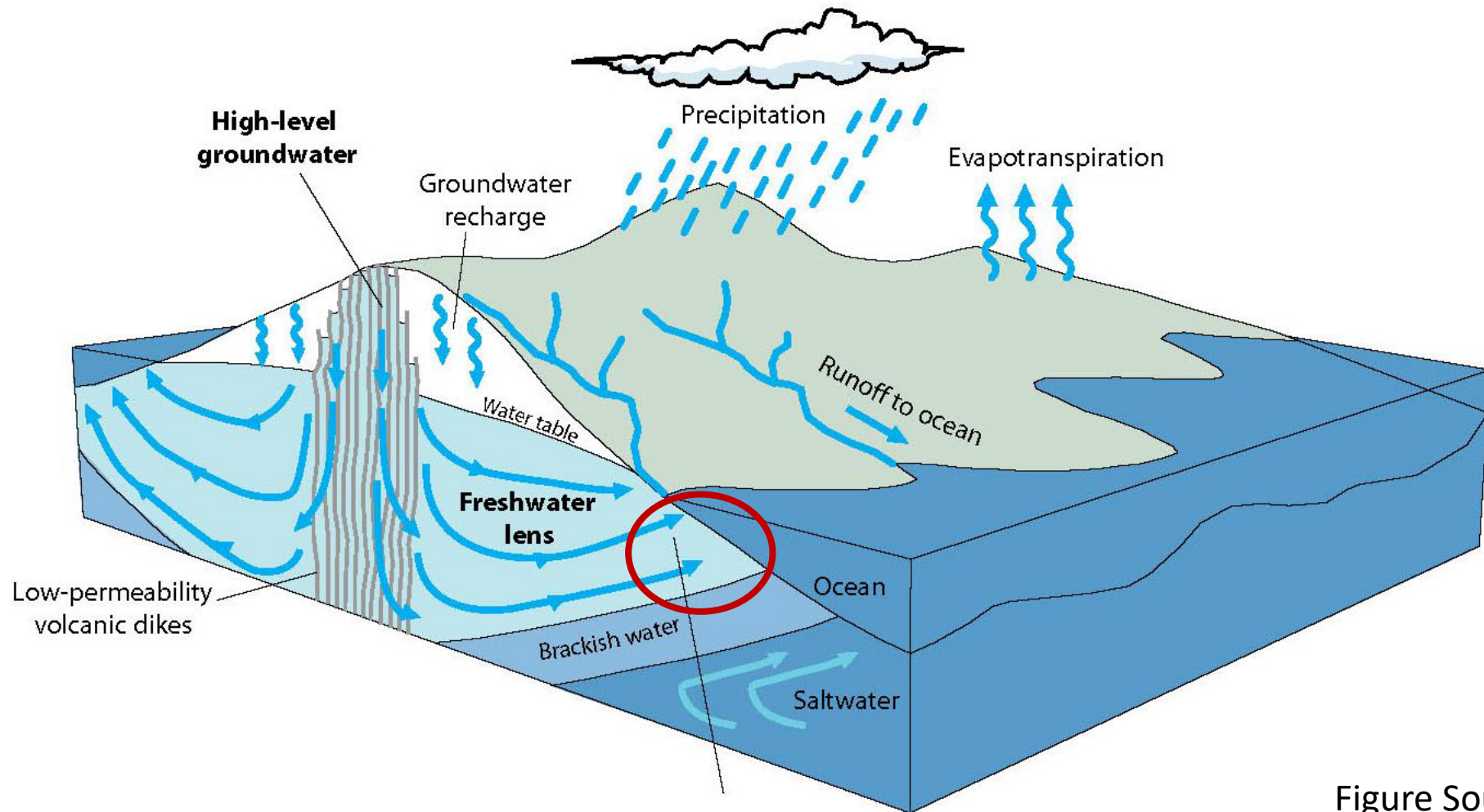
Using deep learning to predict submarine groundwater discharge off the Kona Coast

Trista McKenzie (tristam at hawaii dot edu)

CEE696 Final Project

December 19, 2019

Background



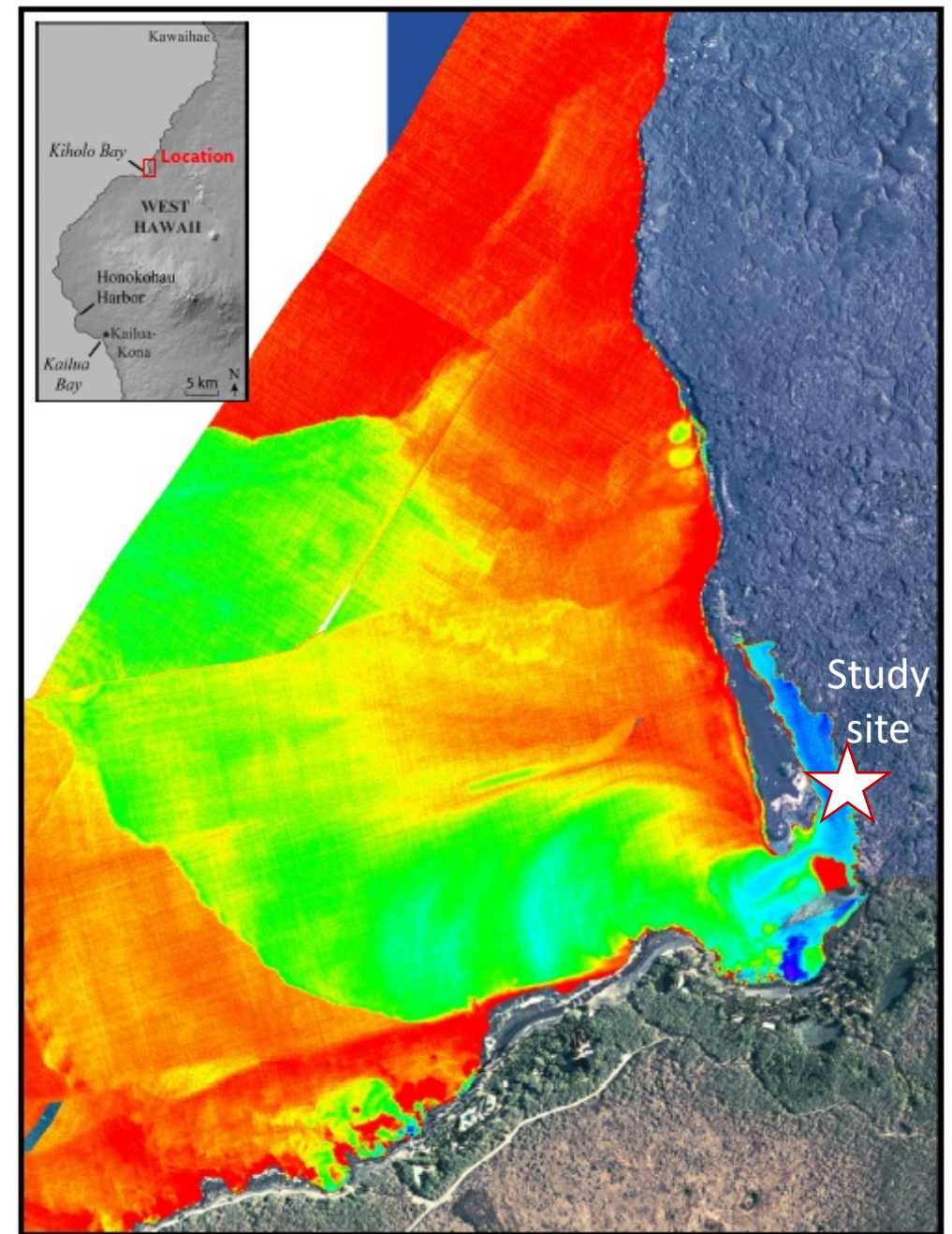
Submarine groundwater discharge (SGD)

Figure Source: USGS, 2015

Study Site

Kīholo Bay, Big Island

- Open Embayment & Lagoon
- No streamflow
- Coastal aquifer: unconfined basal lens and dike impounded water
- SGD along coastline



Panel 15.
NE Kīholo Bay (Apr. 30)

Temperature (°C)
25.0 24.5 24.0 23.5 23.0 22.5 22.1

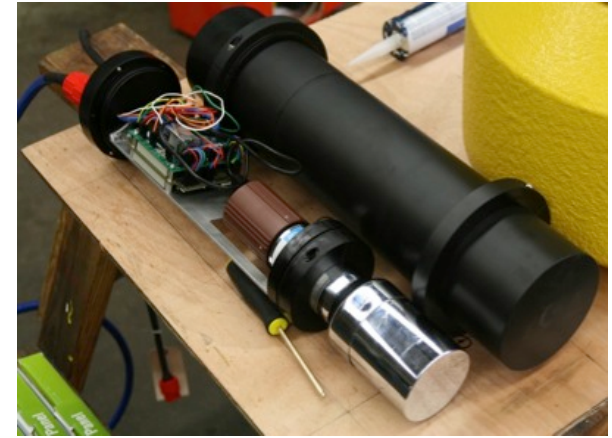
0 100 200 m N
1:10,000

Figure Source: Johnson et al., 2008

Data Acquisition: SGD Sniffer

SGD Sniffer: fully autonomous gamma-spectrometer

- measures ^{222}Rn (radon): groundwater tracer
- 1-hour resolution Rn measurements
- Rn allows for calculation of SGD



Data

- SGD Sniffer deployed in Kīholo Bay 2014-2018
- 18,223 data points
- Tidal effects and seasonality in SGD evidenced by time series data analysis

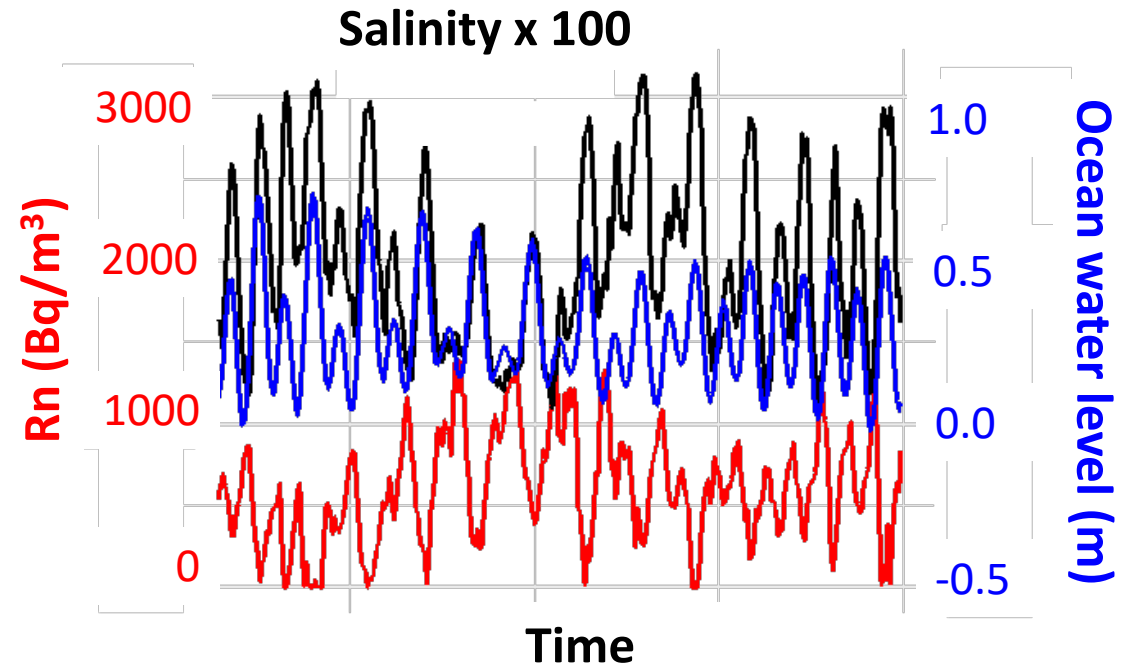


Figure Source: Dulai & Fuleky, 2018

Methods

Input: Rn, Water depth, water temperature, water salinity, groundwater level (USGS), ocean water level (NOAA), air temperature (RAWS), wind speed (RAWS), relative humidity (RAWS), precipitation (RAWS)

Output: SGD

Two models: DNN and CNN with 1DConv



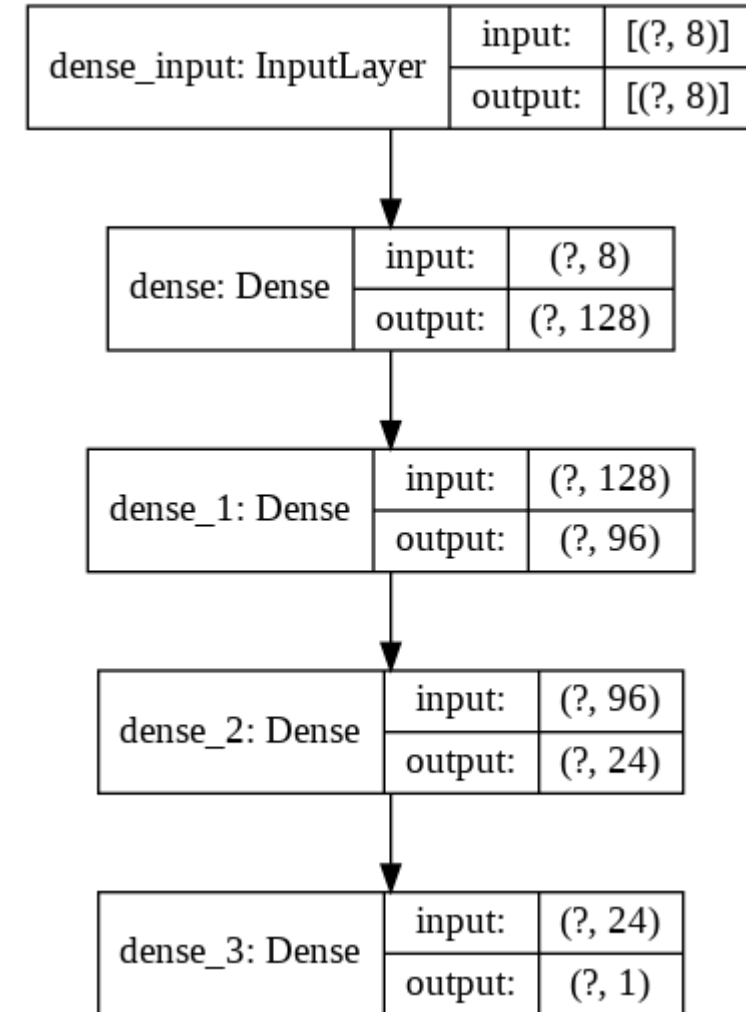
DNN Model

90/10 train/test split

4 fully connected layers

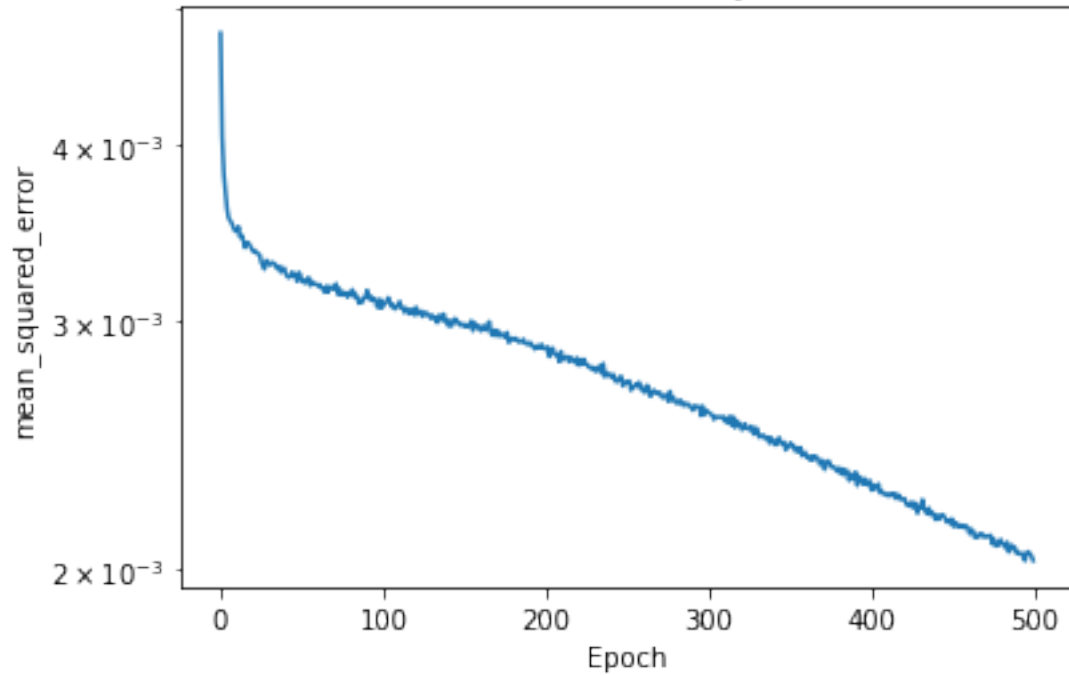
Adam optimizer

```
model1b = tf.keras.Sequential()
model1b.add(Dense(128, activation = 'relu', input_shape = (8,)))
model1b.add(Dense(96, activation = 'sigmoid'))
model1b.add(Dense(24, activation = 'elu'))
model1b.add(Dense(1))
model1b.compile(optimizer = 'adam', loss = 'mean_squared_error', metrics = ['mse'])
model1b.summary()
```

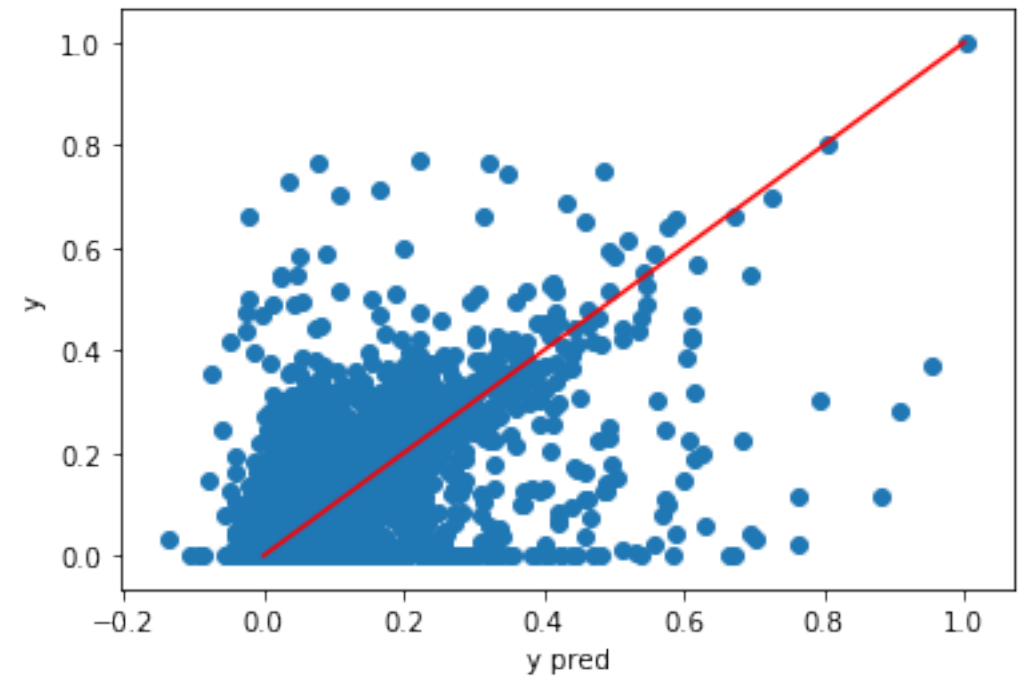
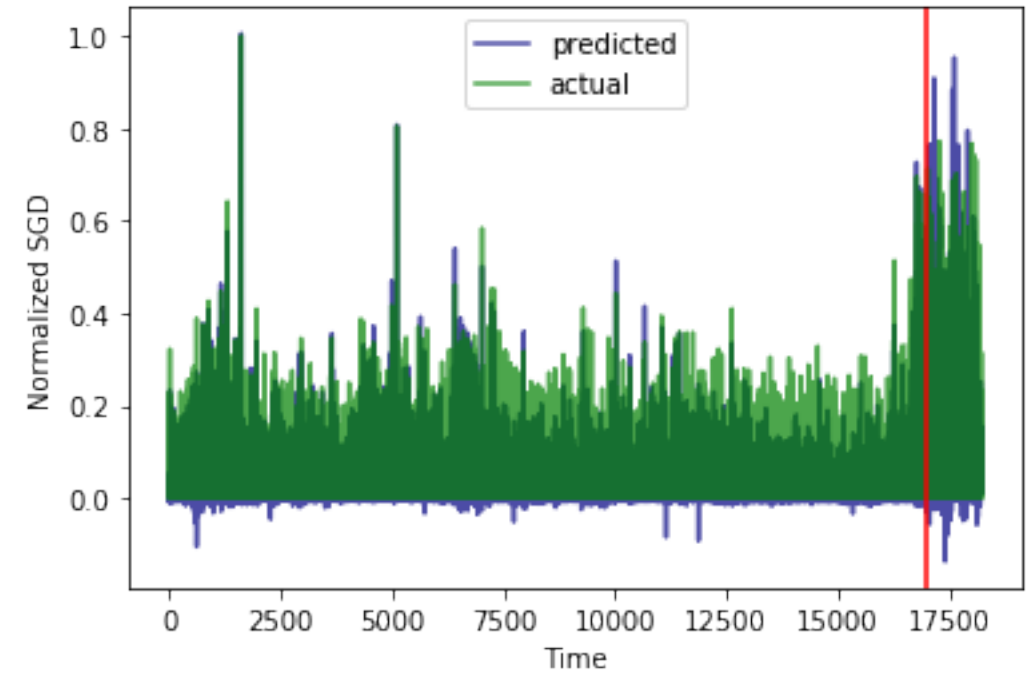


DNN Model Results

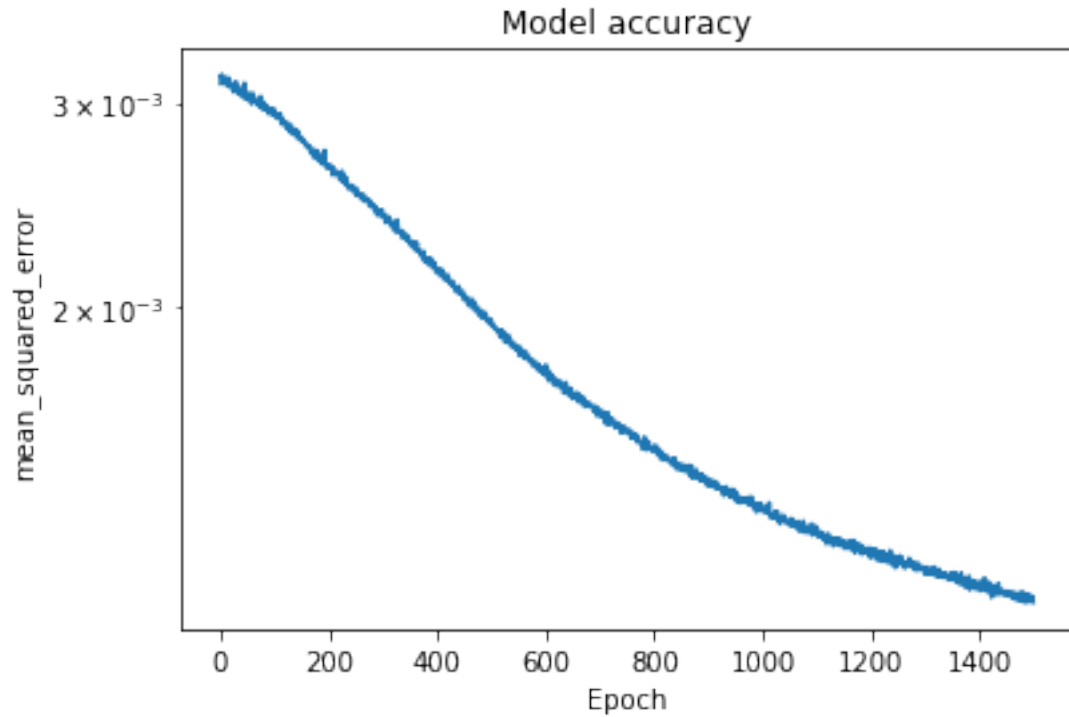
Model accuracy



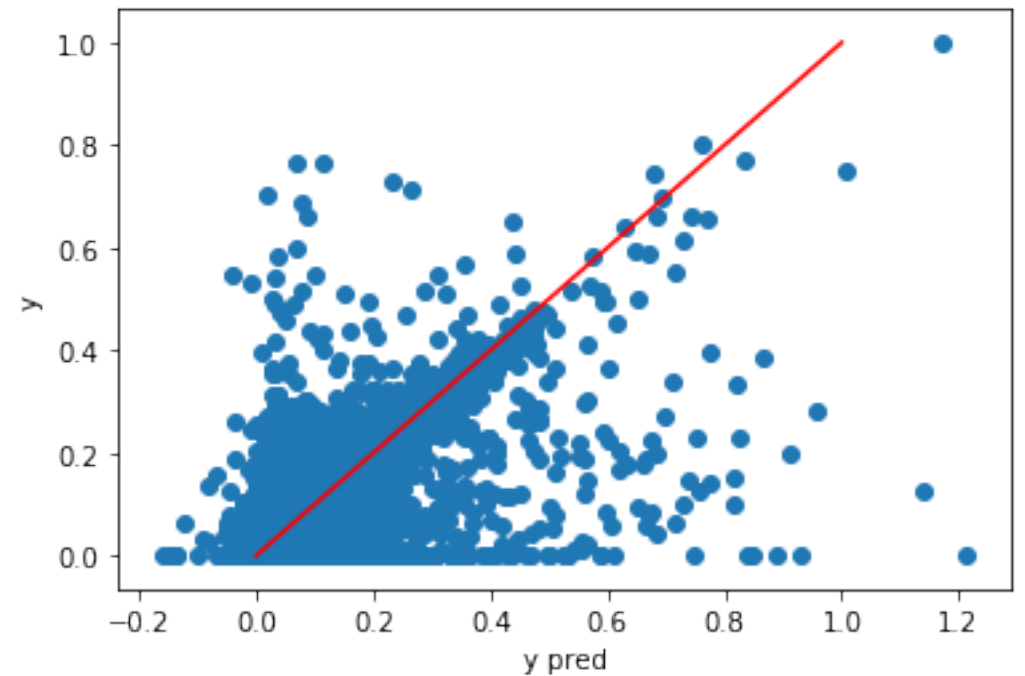
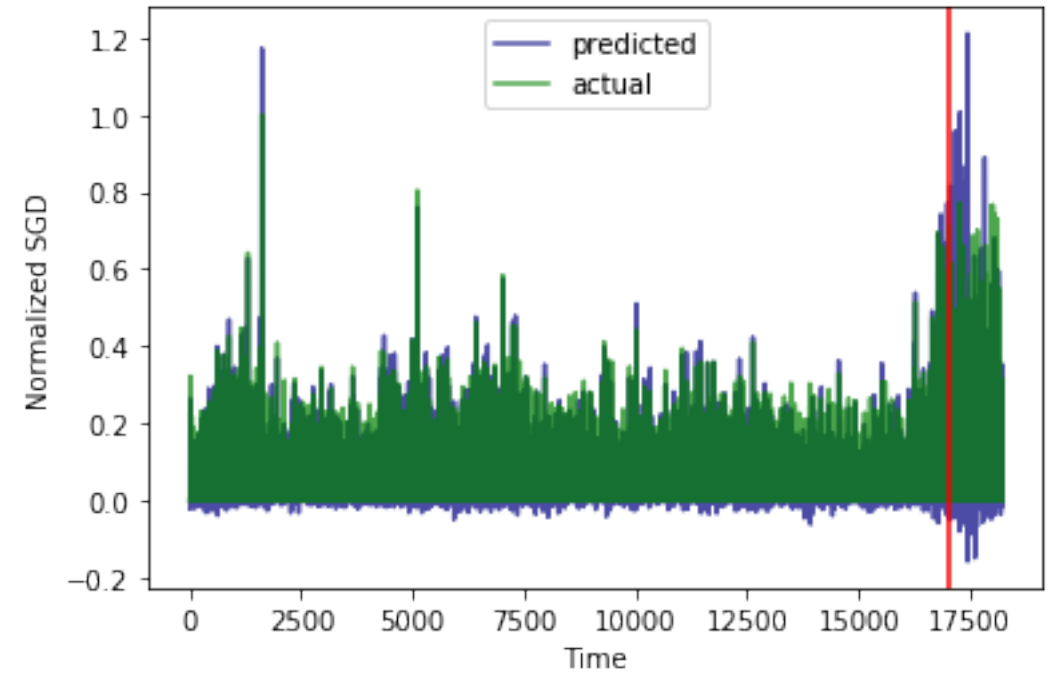
```
hist1b = model1b.fit(x_train1b, y_train1b,  
epochs = 500, batch_size = 6, verbose = 1)
```



DNN Model Results



```
hist1b = model1b.fit(x_train1b, y_train1b,  
epochs = 1500, batch_size = 6, verbose = 1)
```



CNN Model

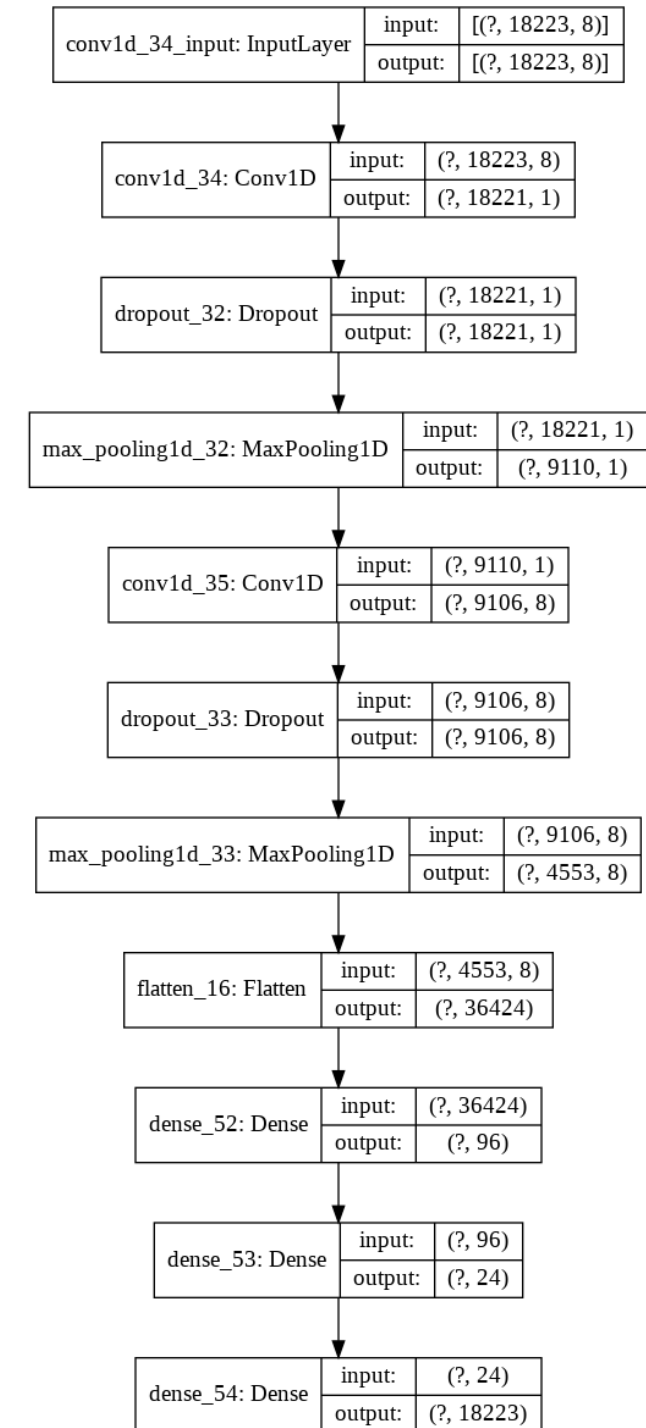
50/50 train/test split

2 CNN

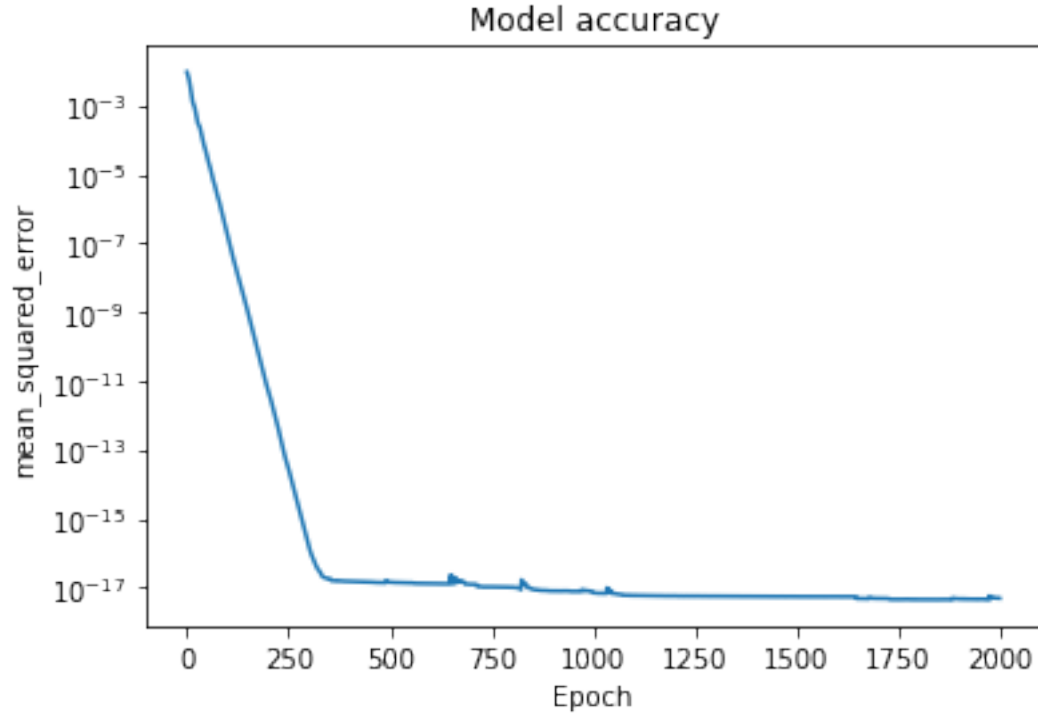
3 fully connected layers

Adam optimizer

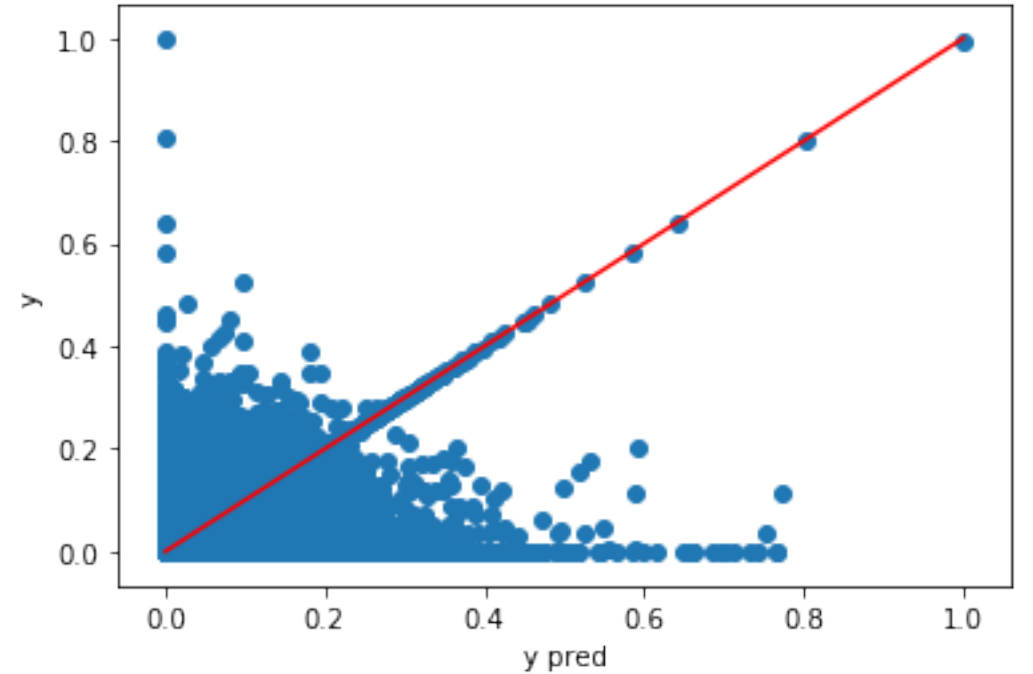
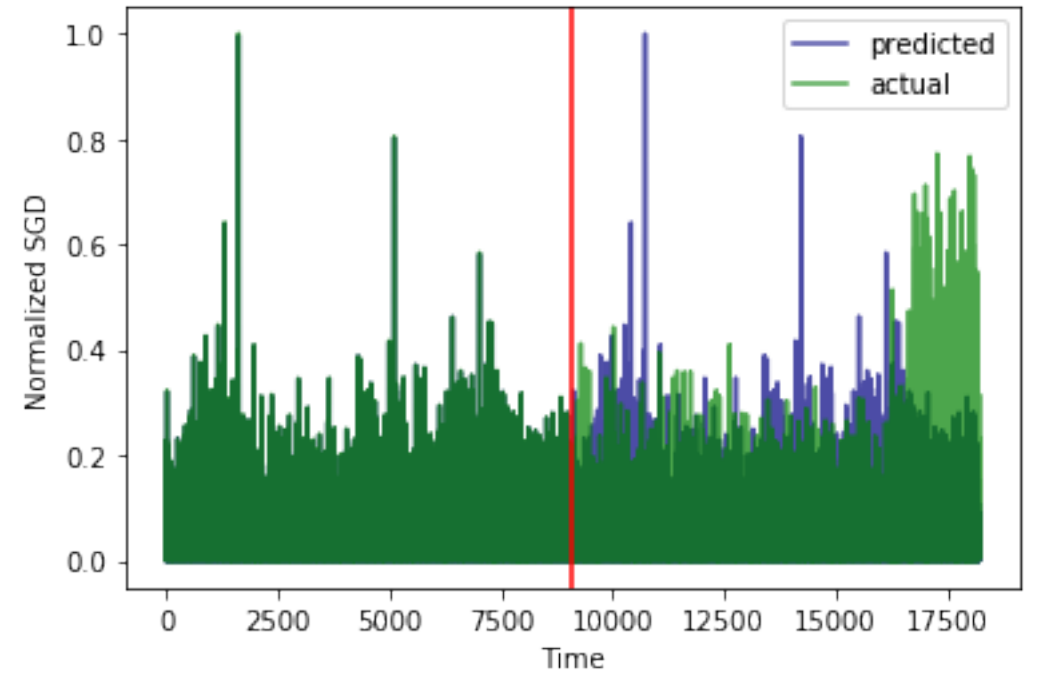
```
model5 = tf.keras.Sequential()
model5.add(Conv1D(filters = 1, kernel_size = 3, activation = 'relu',
input_shape = (N,8)))
model5.add(Dropout(0.5))
model5.add(MaxPooling1D(pool_size = 2))
model5.add(Conv1D(filters = 8, kernel_size = 5, activation = 'relu'))
model5.add(Dropout(0.5))
model5.add(MaxPooling1D(pool_size = 2))
model5.add(Flatten())
model5.add(Dense(96, activation = 'sigmoid'))
model5.add(Dense(24, activation = 'elu'))
model5.add(Dense(N))
model5.compile(loss = 'mean_squared_error', optimizer =
'adam', metrics = ['accuracy'])
```



CNN Model Results



```
hist5 = model5.fit(x1, y1, epochs = 2000,  
batch_size = 12, verbose = 1)
```



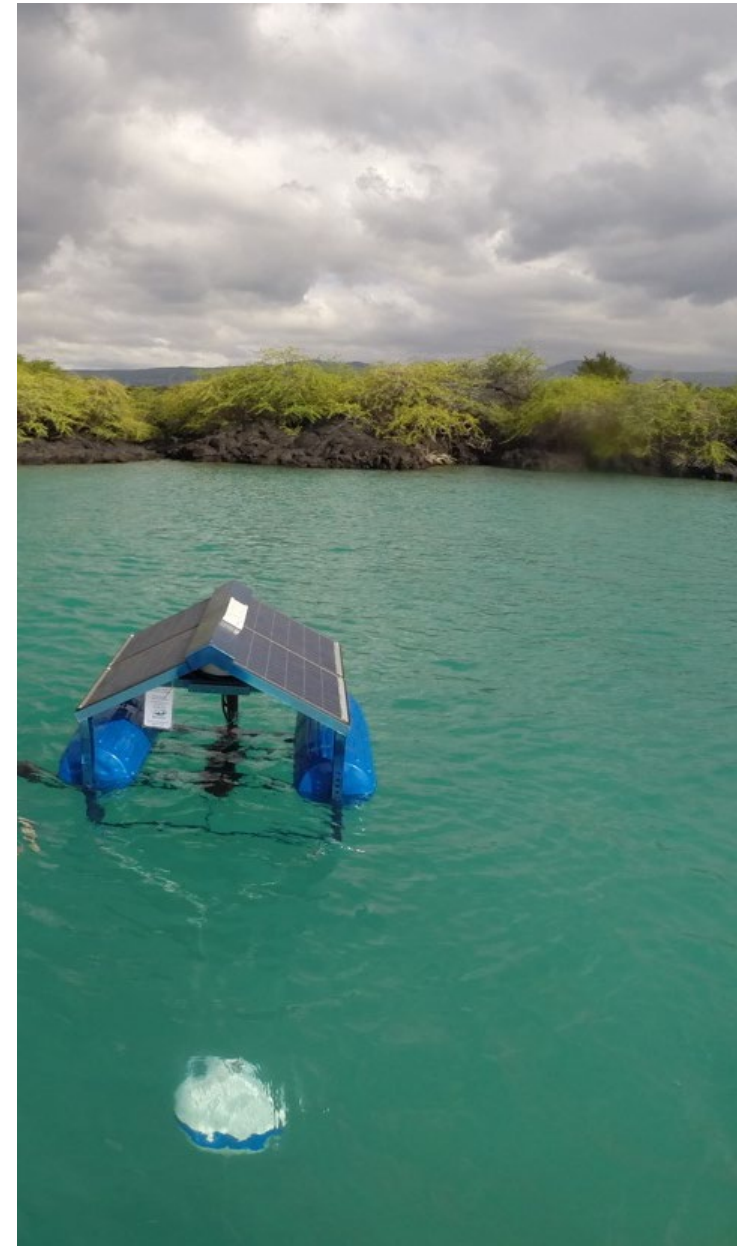
Future Work & Conclusion

Future Work:

1. Improve model accuracy
2. Use model to fill in missing data

Conclusion:

1. The DNN and CNN models show promising results for modeling SGD.



Acknowledgements

SGD Sniffer Fabrication: Dulai et al., 2015

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Thank you!



References

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Dulai & Fuleky, 2018. Time series analysis of a multiyear submarine groundwater discharge record from the Kona coast of Hawaii. EGU Assembly, Vienna, 2018, Abstract HS8.2.10 A.182.

Data obtained from:

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For site: # USGS 083216045 / / 12 / 0 7-4360-01 Kalaoa N. Kona (W12-11), HI

Meteorology: <https://raws.dri.edu/cgi-bin/rawMAIN.pl?hiHPUW>

Ocean Water Level: NOAA Tides & Currents site 1617433

<http://tidesandcurrents.noaa.gov/waterlevels.html?id=1617433&units=metric&bdate=20140313&edate=20140522&timezone=LST&datum=MLLW&interval=h&action=data>